

**GUROBI**  
OPTIMIZATION

# MIP Models and Heuristics

- Tempting to focus exclusively on optimality
  - Comforting to know that you can't find a better solution
- Typically overkill
  - Uncertainty/errors in data
- MIP often used as a heuristic
  - Lower bound is nice
  - Upper bound (feasible solution) is what you typically take away
- Trivial to use MIP solver as a heuristic
  - Just stop before proven optimal solution is found
- This session focuses on advanced techniques
  - MIP starts
  - Variable hints
  - Callbacks

- Three ways to inject solution information:
  - MIP Start
    - Pass a known feasible solution (or partial solution) when optimization starts
    - MIP solver will try to reproduce that solution
      - Limited repair capabilities if that solution is not feasible
  - Variable hints
    - Pass hints about promising values for variables, and relative priorities of those hints
    - Hints used in multiple phases of algorithm
      - Heuristics and branching
  - Callbacks
    - User code called at each node of branch-and-cut tree
    - Can query relaxation solution, and can inject a feasible solution (or partial solution)

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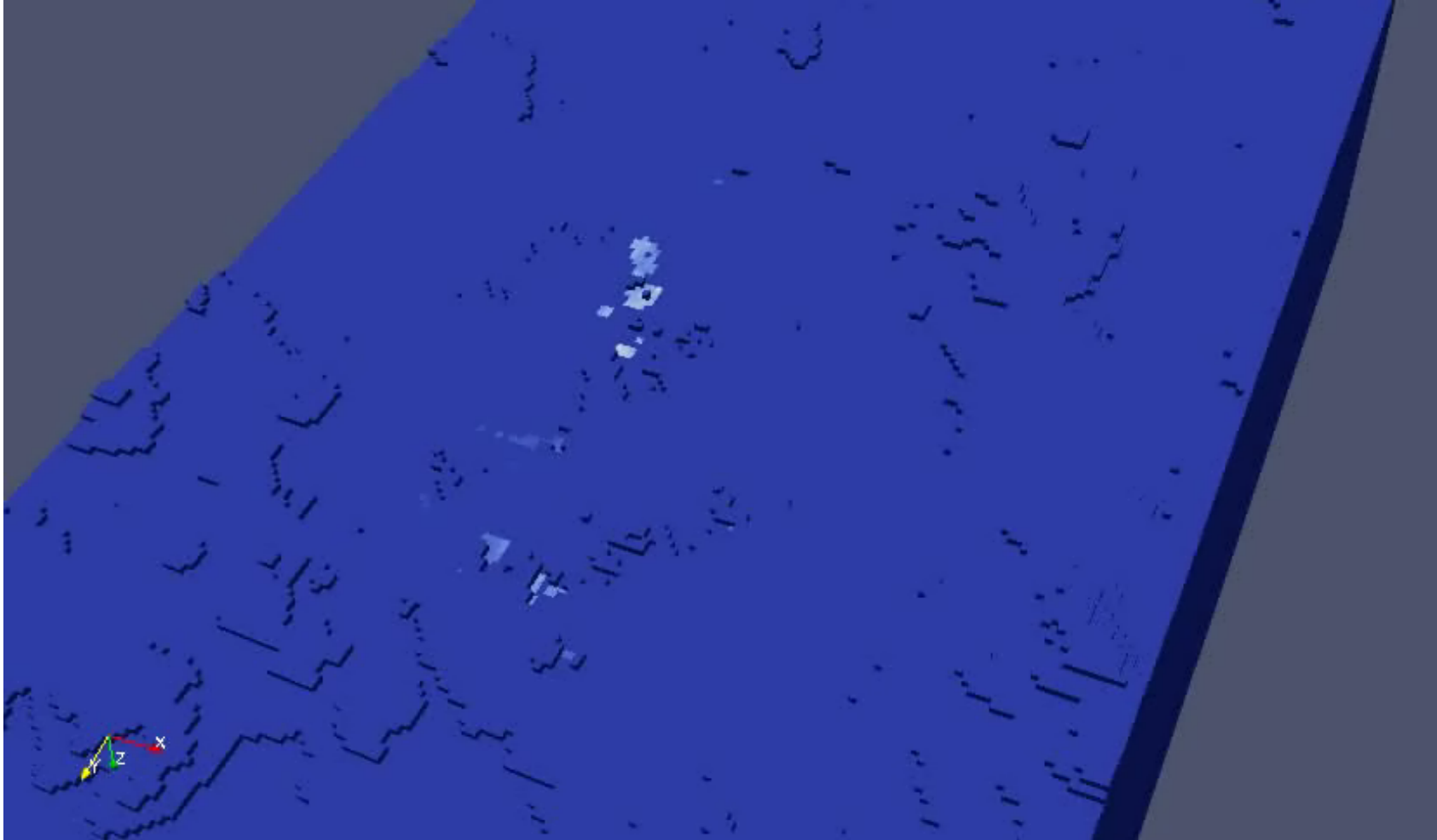
# Combining Solution Schemes

- Often two very different approaches to solving a problem
  - Problem-specific heuristic
  - MIP model
- Problem-specific heuristics have plusses and minuses
  - By utilizing domain information
    - Quick
    - Possibly gives higher-quality initial solution than general-purpose MIP heuristic
  - But:
    - Typically no lower bound
      - No optimality gap information
    - Difficult to implement an exhaustive search
      - No way to get a proven optimal solution
    - Often difficult to extend
      - When problem changes slightly (e.g., new type of constraint)
    - Often difficult to achieve diversity
      - Solution quality may hit a plateau quickly

- Simple solution:
  - Run problem-specific heuristic first
  - Feed result into MIP model as a MIP start
  - Let MIP solver continue to find
    - Lower bound
    - Better solutions



# Example Application – Open-Pit Mining



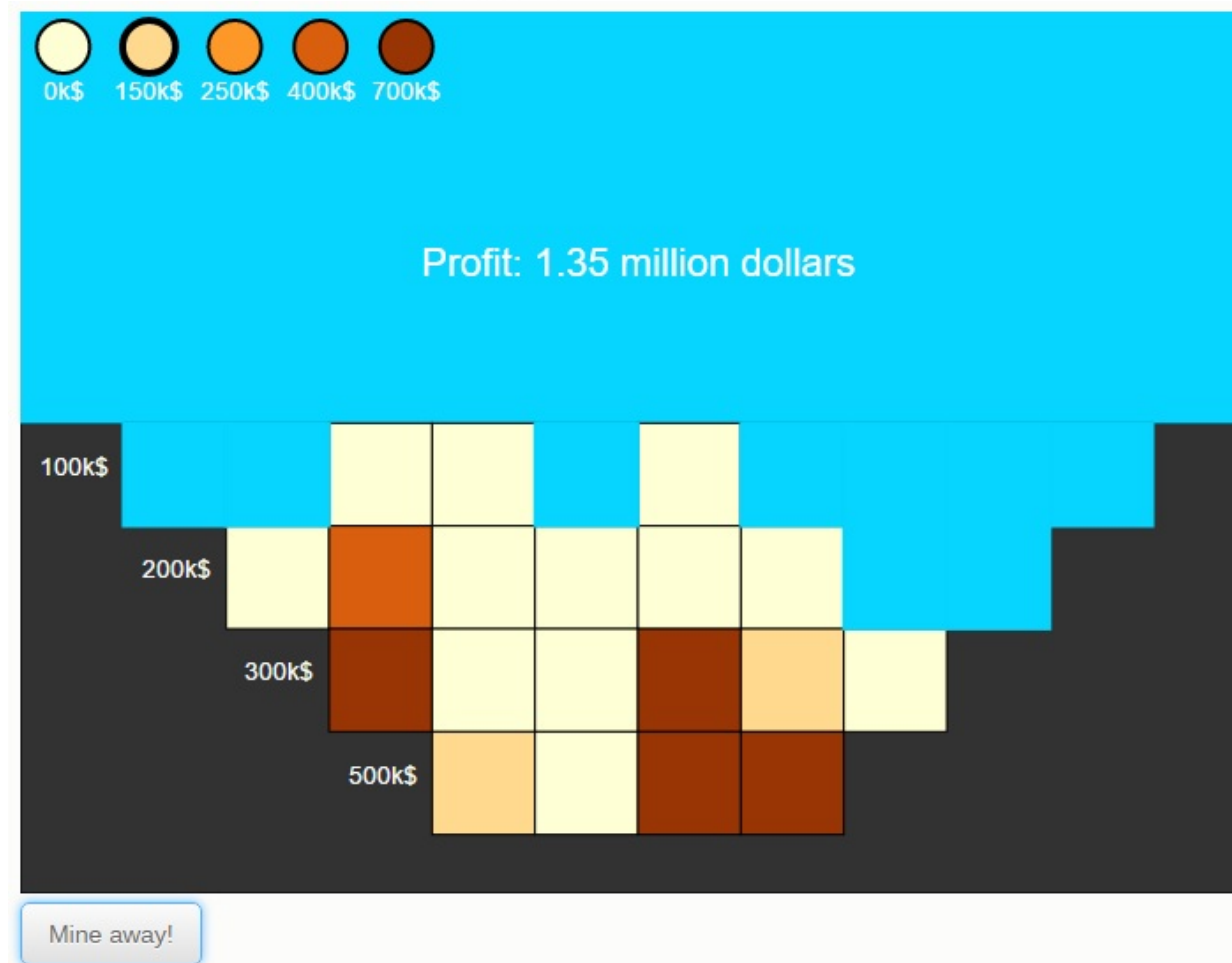
# Open-Pit Mining Model

- Problem:
  - Decide which cells to mine in each time period
- Objective:
  - Mine the cells with the most valuable raw materials
    - Some cells have negative value – cost more to extract than they net in raw material value
- Constraints:
  - Can't mine a cell until after you've mined the cells above it
    - Note: "cells", not "cell" – can't mine a vertical hole
      - Limit slope to reduce chance of a cave-in
      - Trucks need to drive down to haul out dirt
  - Limited capacity to pull dirt out of the ground per time period
    - Limited number of trucks
    - Raw material extraction facilities have limited capacity



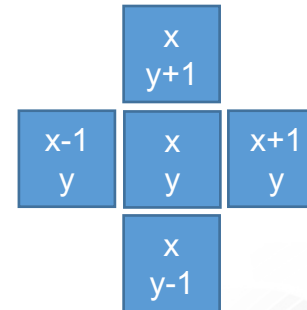
# Open-Pit Mining Model – 2-D Slice

- Visit <http://examples.gurobi.com/open-pit-mining> for an interactive mining example...



# Open-Pit Mining Model

- Simple example 3-D mining model:
  - Variables:
    - $\text{mined}_{x,y,z,t}$ : binary, determines whether cell at grid location  $(x,y,z)$  has been mined at (or before) time  $t$
  - Constraints:
    - Precedence:
      - Time:  $\text{mined}_{x,y,z,t} \geq \text{mined}_{x,y,z,t-1}$
      - Space:  $\text{mined}_{x,y,z,t} \leq \text{mined}_{x,y,z+1,t}$   
 $\text{mined}_{x,y,z,t} \leq \text{mined}_{x-1,y,z+1,t}$   
 $\text{mined}_{x,y,z,t} \leq \text{mined}_{x+1,y,z+1,t}$   
 $\text{mined}_{x,y,z,t} \leq \text{mined}_{x,y-1,z+1,t}$   
 $\text{mined}_{x,y,z,t} \leq \text{mined}_{x,y+1,z+1,t}$
    - Capacity:
      - $\sum_{x,y,z} (\text{mined}_{x,y,z,t} - \text{mined}_{x,y,z,t-1}) \leq \text{capacity}_t$



# Solving the Open-Pit Mining Problem



- Default settings:

Optimize a model with 167806 rows, 33556 columns and 449282 nonzeros

Variable types: 0 continuous, 33556 integer (33556 binary)

Coefficient statistics:

Matrix range [9e-01, 1e+00]

Objective range [4e-07, 4e-01]

Bounds range [1e+00, 1e+00]

RHS range [1e+02, 1e+02]

Found heuristic solution: objective 10.7392

Presolve time: 3.34s

Presolved: 167806 rows, 33556 columns, 449282 nonzeros

Variable types: 0 continuous, 33556 integer (33556 binary)

...

# Solving the Open-Pit Mining Problem

Root simplex log...

| Iteration | Objective     | Primal Inf.  | Dual Inf.    | Time |
|-----------|---------------|--------------|--------------|------|
| 3270      | 1.0033671e+03 | 0.000000e+00 | 6.021110e+04 | 5s   |
| 15260     | 7.6003191e+02 | 0.000000e+00 | 1.472755e+05 | 10s  |
| 26160     | 6.8283505e+02 | 0.000000e+00 | 5.575091e+04 | 15s  |
| 36406     | 6.3195748e+02 | 0.000000e+00 | 4.191839e+04 | 20s  |
| 44690     | 6.0376674e+02 | 0.000000e+00 | 7.441997e+04 | 25s  |
| ...       |               |              |              |      |
| 117938    | 4.5763821e+02 | 0.000000e+00 | 1.412679e+04 | 70s  |
| 124042    | 4.5423261e+02 | 0.000000e+00 | 8.671474e+03 | 75s  |
| 130364    | 4.5196987e+02 | 0.000000e+00 | 2.823627e+03 | 80s  |
| 135145    | 4.5135892e+02 | 0.000000e+00 | 0.000000e+00 | 84s  |
| 135145    | 4.5135892e+02 | 0.000000e+00 | 0.000000e+00 | 84s  |

Root relaxation: objective 4.513589e+02, 135145 iterations, 80.59 seconds

# Solving the Open-Pit Mining Problem

| Nodes |        |   | Current Node |       |        | Objective Bounds |           |       | Work    |      |
|-------|--------|---|--------------|-------|--------|------------------|-----------|-------|---------|------|
| Expl  | Unexpl |   | Obj          | Depth | IntInf | Incumbent        | BestBd    | Gap   | It/Node | Time |
|       | 0      | 0 | 451.35892    | 0     | 996    | 10.73916         | 451.35892 | 4103% | –       | 85s  |
| H     | 0      | 0 |              |       |        | 448.0396048      | 451.35892 | 0.74% | –       | 93s  |
| H     | 0      | 0 |              |       |        | 450.3822401      | 451.35892 | 0.22% | –       | 99s  |
|       | 0      | 0 | 451.33446    | 0     | 977    | 450.38224        | 451.33446 | 0.21% | –       | 106s |
| H     | 0      | 0 |              |       |        | 450.5145733      | 451.33446 | 0.18% | –       | 112s |

- First MIP solution is terrible
- Exploit domain information to find a better one?
- Trivial "greedy" heuristic:
  - Repeat
    - Pick the 'exposed' cell with the largest profit (or smallest loss)
    - If we don't have sufficient capacity in this time period
      - Advance the time period  $t$
    - Mine the cell
      - Possibly creating new 'exposed' cells
- Choose the best solution found along the way
  - Set it as a MIP start

- "Set it as a MIP start"
- Mechanics?

```
# Call greedy heuristic
# Return solution in dictionary greedy_x
greedy_x = {}
greedy_heur(model, greedy_x)

# Populate 'start' attribute from greedy solution
for v in vars:
    v.start = greedy_x[v]
```



# Quick Aside: Partial MIP Start

- Note: you don't need to provide start values for every variable
- Solver will perform a truncated sub-MIP solve to try to complete your start
  - Fix all variables with provided start values
  - Solve a MIP on the remaining variables
    - Using a node limit (limit controlled by `SubMIPNodes` parameter)
- Need to use some caution
  - For example, we'll accept a MIP start with only one value
  - Resulting sub-MIP can be expensive

# Solving the Open-Pit Mining Problem

- With trivial heuristic:

```
Presolved: 167806 rows, 33556 columns, 449282 nonzeros
```

```
Loaded MIP start with objective 428.813
```

```
Variable types: 0 continuous, 33556 integer (33556 binary)
```

```
...
```

- Runtime for heuristic:
  - Less than 1s

# Solving the Open-Pit Mining Problem

- If you let it run for a while...

| Nodes  |        | Current Node |       |        | Objective Bounds |           |       | Work    |      |
|--------|--------|--------------|-------|--------|------------------|-----------|-------|---------|------|
| Expl   | Unexpl | Obj          | Depth | IntInf | Incumbent        | BestBd    | Gap   | It/Node | Time |
| ...    |        |              |       |        |                  |           |       |         |      |
| H 1055 | 938    |              |       |        | 450.6810903      | 451.30920 | 0.14% | 33.7    | 303s |
| 1061   | 944    | 451.17448    | 19    | 779    | 450.68109        | 451.30920 | 0.14% | 34.8    | 307s |
| 1070   | 952    | 451.12340    | 25    | 642    | 450.68109        | 451.30920 | 0.14% | 35.1    | 311s |
| 1202   | 1069   | 451.19371    | 12    | 1176   | 450.68109        | 451.30920 | 0.14% | 35.3    | 374s |
| 1204   | 1070   | 451.27392    | 6     | 996    | 450.68109        | 451.27392 | 0.13% | 35.3    | 419s |
| 1205   | 1071   | 451.09846    | 48    | 1124   | 450.68109        | 451.26803 | 0.13% | 35.2    | 446s |
| 1206   | 1072   | 450.84933    | 78    | 1146   | 450.68109        | 451.26775 | 0.13% | 35.2    | 457s |
| H 1206 | 1018   |              |       |        | 450.7981045      | 451.26019 | 0.10% | 35.2    | 482s |
| 1208   | 1019   | 451.20933    | 45    | 1293   | 450.79810        | 451.25898 | 0.10% | 35.1    | 489s |
| 1209   | 1020   | 451.09179    | 45    | 1265   | 450.79810        | 451.25705 | 0.10% | 35.1    | 500s |

- "Rolling horizon" heuristic:
  - Start from greedy heuristic solution
  - Repeat
    - Choose a contiguous set of time periods (e.g. periods 3-6)
    - Freeze mining decisions from current solution outside of this period
    - Reoptimize decisions within this period
      - As a MIP
      - May produce a better solution
- Much more expensive than greedy heuristic alone
  - Solve multiple, smaller MIPs
  - Total runtime ~60s
- Also much more effective...

Loaded MIP start with objective 450.802

- If you let it run for a while...

| Nodes |        | Current Node |           |        | Objective Bounds |             |           | Work    |           |
|-------|--------|--------------|-----------|--------|------------------|-------------|-----------|---------|-----------|
| Expl  | Unexpl | Obj          | Depth     | IntInf | Incumbent        | BestBd      | Gap       | It/Node | Time      |
| ...   |        |              |           |        |                  |             |           |         |           |
|       | 0      | 2            | 451.31249 | 0      | 1176             | 450.80167   | 451.31249 | 0.11%   | – 219s    |
|       | 3      | 8            | 451.30992 | 2      | 1120             | 450.80167   | 451.31154 | 0.11%   | 12.7 220s |
|       | 57     | 58           | 451.28197 | 16     | 789              | 450.80167   | 451.30960 | 0.11%   | 26.8 227s |
|       | 79     | 82           | 451.23186 | 21     | 637              | 450.80167   | 451.30960 | 0.11%   | 51.6 232s |
| H     | 98     | 82           |           |        |                  | 450.8080003 | 451.30960 | 0.11%   | 43.5 233s |
|       | 159    | 159          | 451.22172 | 41     | 660              | 450.80800   | 451.30960 | 0.11%   | 31.9 238s |
| H     | 185    | 159          |           |        |                  | 450.8151686 | 451.30960 | 0.11%   | 30.3 238s |
|       | 308    | 311          | 451.19004 | 69     | 585              | 450.81517   | 451.30960 | 0.11%   | 27.1 244s |
| H     | 549    | 532          |           |        |                  | 450.8286395 | 451.30960 | 0.11%   | 24.3 253s |
|       | 1114   | 998          | 450.96504 | 100    | 1176             | 450.82864   | 451.30762 | 0.11%   | 24.8 342s |
|       | 1116   | 999          | 451.13381 | 34     | 996              | 450.82864   | 451.27350 | 0.10%   | 24.7 370s |
|       | 1121   | 1003         | 451.14416 | 24     | 1129             | 450.82864   | 451.24033 | 0.09%   | 24.6 421s |

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- User code called at each node of branch-and-cut tree
    - Can query relaxation solution, and can inject a feasible solution (or partial solution)

# Variable Hints – Use Cases

- Sliding time window
  - Model solves for a window of time ( $t=0,1,2,\dots,n$ )
  - Given a solution for  $t=0\dots n$ :
    - Deploy solution for  $t=0$
    - Gather new measured data
    - Create updated model for  $t=1\dots n+1$
  - Can use  $t=1\dots n$  solution from first model as hint for next model



# Variable Hints – Use Cases

- Multiple scenarios
  - Solve multiple variants of the same model
  - Small perturbation to obj, RHS, etc.
  - Often lots of overlap between high-quality solutions
    - Small perturbation won't completely change the character of the solution
  - Use solutions from other scenarios as hints

# Variable Hints – Multiple Scenario Example



- Read a difficult model from a file
- Solve it 10 times with perturbed objectives
  - Count # times each binary variable takes value 0/1
- Use more common value as hint value
  - # of times it takes that value as hint priority

# Variable Hints – Multiple Scenario Example

```
m = read('ljb12')
perturb = 1.2
for i in range(REPS):
    # perturb objective
    for v in binaries:
        v.obj = random.uniform(1/perturb, perturb) * v.obj +
                random.uniform(-1e-4, 1e-4)

m.reset()
m.optimize()

# adjust counts
for v in binaries:
    val = int(round(v.x))
    count[v][val] = count[v][val] + 1
```

# Variable Hints – Multiple Scenario Example

```
for i in range(REPS):
    # perturb objective
    ...
    # solve without hints
    ...
    # solve with hints
m.reset()
for v in binaries:
    if count[v][0] > count[v][1]:
        v.varhintval = 0
        v.varhintpri = count[v][0]
    elif count[v][0] < count[v][1]:
        v.varhintval = 1
        v.varhintpri = count[v][1]
m.optimize()
```

# Variable Hints – Multiple Scenario Example

- Using 10 second time limit for 'training' runs and 1 second time limit for tests

|         |                           |                       |
|---------|---------------------------|-----------------------|
| Trial 0 | no hint obj: 1.00000e+100 | hint obj: 5.90331e+00 |
| Trial 1 | no hint obj: 1.00000e+100 | hint obj: 5.95868e+00 |
| Trial 2 | no hint obj: 1.00000e+100 | hint obj: 5.93106e+00 |
| Trial 3 | no hint obj: 1.00000e+100 | hint obj: 6.31872e+00 |
| Trial 4 | no hint obj: 1.00000e+100 | hint obj: 6.02026e+00 |
| Trial 5 | no hint obj: 1.00000e+100 | hint obj: 5.95413e+00 |
| Trial 6 | no hint obj: 1.00000e+100 | hint obj: 5.93878e+00 |
| Trial 7 | no hint obj: 1.00000e+100 | hint obj: 5.97493e+00 |
| Trial 8 | no hint obj: 1.00000e+100 | hint obj: 6.38623e+00 |
| Trial 9 | no hint obj: 1.00000e+100 | hint obj: 6.11830e+00 |

# Variable Hints – Multiple Scenario Example

- Using 20 second time limit for 'training' runs and 2 second time limit for tests

|         |                          |                       |
|---------|--------------------------|-----------------------|
| Trial 0 | no hint obj: 6.38623e+00 | hint obj: 5.88125e+00 |
| Trial 1 | no hint obj: 6.38623e+00 | hint obj: 5.80083e+00 |
| Trial 2 | no hint obj: 6.38623e+00 | hint obj: 5.76273e+00 |
| Trial 3 | no hint obj: 6.38623e+00 | hint obj: 5.78522e+00 |
| Trial 4 | no hint obj: 6.38623e+00 | hint obj: 5.87428e+00 |
| Trial 5 | no hint obj: 6.38623e+00 | hint obj: 5.79409e+00 |
| Trial 6 | no hint obj: 6.38623e+00 | hint obj: 5.74034e+00 |
| Trial 7 | no hint obj: 6.15425e+00 | hint obj: 5.84347e+00 |
| Trial 8 | no hint obj: 6.38623e+00 | hint obj: 5.76325e+00 |
| Trial 9 | no hint obj: 6.38623e+00 | hint obj: 5.73973e+00 |

# Variable Hints – Multiple Scenario Example

- What are hints doing...?

Root relaxation: objective -5.311377e-01, 2533 iterations, 0.01 seconds

| Nodes                            |        | Current Node |          |        | Objective Bounds |          |          | Work    |      |
|----------------------------------|--------|--------------|----------|--------|------------------|----------|----------|---------|------|
| Expl                             | Unexpl | Obj          | Depth    | IntInf | Incumbent        | BestBd   | Gap      | It/Node | Time |
| 0                                | 0      | -0.53114     | 0        | 2424   | -                | -0.53114 | -        | -       | 0s   |
| 0                                | 0      | -0.23949     | 0        | 2145   | -                | -0.23949 | 104%     | -       | 0s   |
| New incumbent: VarHint heuristic |        |              |          |        |                  |          |          |         |      |
| H                                | 0      | 0            |          |        | 5.8114413        | -0.23949 | 104%     | -       | 1s   |
|                                  | 0      | 0            | -0.22284 | 0      | 2145             | 5.81144  | -0.22284 | 104%    | 1s   |



# Variable Hints – Multiple Scenario Example



- Note: this isn't actually that effective of a strategy in general
  - But it is extremely effective on some models
- Key point
  - If you know something about what good solutions look like, try using variable hints to pass this info to us

- Three ways to inject solution information:
  - MIP Start
    - Pass a known feasible solution (or partial solution) when optimization starts
    - MIP solver will try to reproduce that solution
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  - Variable hints
    - Pass hints about promising values for variables, and relative priorities of those hints
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      - Heuristics and branching
  - Callbacks
    - User code called at each node of branch-and-cut tree
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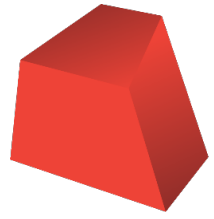
- At each node in B&B search...
  - User routine is called, and can query...
    - Node relaxation solution
    - New feasible solution
  - Can return a solution (or partial solution)

# Open-Pit Mining Revisited

- Return to open-pit mining example
- Original greedy heuristic:
  - Choose exposed cells based on objective value
  - Doesn't require a relaxation solution
- New greedy heuristic:
  - Choose exposed cells based on relaxation value
  - Uses LP solution to choose promising cells
    - Much less "greedy" – LP looks ahead in time
- Can run it at every node, every 10<sup>th</sup> node, etc.

# Open-Pit Mining Revisited

- Results:
  - Tried many different variants
  - Quite good at finding 'good' solutions
  - Doesn't find better solutions
- General MIP heuristics are quite effective
  - Don't expect to be able to beat them very often



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OPTIMIZATION

# Thank you – Questions?